

Some results on Semi-Generalized Recurrent α -cosymplectic manifolds

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Abstract

The object of the present paper is to study some geometrical properties of a semi-generalized recurrent α -Cosymplectic manifolds.

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1. Introduction

The idea of recurrentmanifold was introduced by Walker (1950). On the other hand De and Guha (1991) introduced generalized recurrent manifold with the non-zero 1-form A and another non-zero associated 1-form B. Such a manifold has been denoted by GK_n . If the associated 1-form B becomes zero, then the manifold GK_n reduces to a recurrent manifold introduced by Ruse (1951) which is denoted by K_n . A Riemannian manifold (M^n, g) is called a semi-generalized recurrent manifold (Prasad, 2000) if its curvature tensor Rsatisfies the condition

$$(\nabla_X R)(Y, Z)W = A(X)R(Y, Z)W + B(X)g(Z, W)Y, \tag{1}$$

Where A and B are two 1-forms, Bis non-zero, P and Q are two vector fields such that

$$g(X, P) = A(X), g(X, Q) = B(X),$$
 (2)

for any vector field X and ∇ denotes the operator of covariant differentiation with respect to the metric g.

The notion of almost α -cosymplectic manifolds is introduced by Kim and Pak (2005), where α is a scalar but it need not be constant. In Kumar *et al.*, 2000, the author studied some curvature conditions on α -cosymplectic manifolds. Recently Kumar *et.al.* (2010) studied semi generalized recurrent LP –Sasakian manifolds and obtained interesting results. In this

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paper we study some properties of semi-generalized recurrent α -cosymplectic manifolds. The paper is organized as follows: In section 2,we give a brief account of an α -cosymplectic manifolds and Einstein manifold.

In section 3, we study a semi-generalized recurrent α -cosymplectic manifold. Section 4, deals with semi-generalized φ -recurrent α -cosymplectic manifolds. In the last section, it is proved that a semi-generalized M-projective φ -recurrent α -cosymplectic manifold is an Einstein manifold.

2. Preliminaries

Let M^n be an n-dimensional differentiable manifold equipped with a triple (φ, ξ, η) where φ is a (1-1) tensor field, ξ is a vector field, η is a 1-form on M^n such that

$$\eta(\xi) = 1, \qquad \varphi^2 = -I + \eta \otimes \xi, \qquad (3)$$

which implies

$$\varphi \xi = 0, \eta \circ \varphi = 0, \qquad rank(\varphi) = n - 1.$$
 (4)

If M^n admits a Riemannian metric g, such that

$$g(\varphi X, \varphi Y) = g(X, Y) - \eta(X)\eta(Y),\tag{5}$$

Then M^n is said to admit almost contact structure (φ, ξ, η, g) . On such a manifold, the fundamental Φ on M^n is defined as

$$\Phi(X, Y) = g(\varphi X, Y),$$
 $X, Y \in \Gamma(TM).$

An almost contact metric manifold $(M, \varphi, \xi, \eta, g)$ is said to be almost cosymplectic if $d\eta=0$ and $d\Phi=0$, where d is the exterior differential operator. The products of almost Kaehlerian manifolds and the real line \mathbb{R} or the S^1 circle are the simplest examples of almost cosymplectic manifold. An almost contact manifold $(M, \varphi,)$ is said to be normal if the Nijenhuis torsion

$$N_{\alpha}(X, Y) = [\varphi X, \varphi Y] - \varphi[\varphi X, Y] - \varphi[X, \varphi Y] + \varphi^{2}[X, Y] + 2d\eta(X, Y)\xi,$$

vanishes for any vector fields X and Y. A normal almost cosymplectic manifold is called a cosymplectic manifold. As it is known that an almost contact metric structure is cosymplectic if and only if both $\nabla \eta$ and $\nabla \Phi$ vanish. An almost contact metric manifold M^n is said to be almost α -Kenmotsu if $d\eta$ =0 and $d\Phi$ =2 α η \wedge Φ , α being a non-zero real constant. It is worthwhile to note that almost α -kenmotsu structures are related to some special local conformal deformations of almost cosymplectic structures. In order to treat these two classes in a unified way, we have a new notion of an almost α -cosymplectic manifold for any real number α that is defined as in the formula

$$d\eta = 0$$
, and $d\Phi = 2\alpha \eta \wedge \Phi$.

A normal almost α -cosymplectic manifold is called an α -cosymplectic manifold. An α -cosymplectic manifold is either cosymplectic under the condition $\alpha=0$ or α -kenmotsu under the conditions $\alpha\neq 0$ for $\alpha\in\mathbb{R}$.

On such an α -cosymplectic manifold, we have

$$(\nabla_X \varphi)(Y) = \alpha [g(\varphi X, Y)\xi - \eta(Y)\varphi X], \tag{6}$$

for $\alpha \in \mathbb{R}$ on M^n .

Let M be a n-dimensional α -cosymplectic manifold. From equation (6), it is easy to see that

$$\nabla_X \xi = -\alpha \varphi^2 X,\tag{7}$$

where V denotes the Riemannian connection.

In an α -cosymplectic manifold M^n , the following relations hold:

$$R(\xi, X) Y = \alpha^{2} [\eta(Y) X - g(X, Y)], \tag{8}$$

$$R(X, Y)\xi = \alpha^{2}[\eta(X) Y - \eta(Y) X], \tag{9}$$

$$S(\xi, X) = -\alpha^2(n-1)\eta(X)$$
 (10)

$$S(\varphi X, \varphi Y) = S(X, Y) + \alpha^2 (n - 1)\eta(X)\eta(Y) \tag{11}$$

$$R(\xi, X)\xi = \alpha^2 [X - \eta(X)\xi], \tag{12}$$

$$g(R(\xi, X)Y, \xi) = \alpha^2 [\eta(X)\eta(Y) - g(X, Y)], \tag{13}$$

$$Q\xi = -\alpha^2(n-1)\xi,\tag{14}$$

$$S(\xi, \xi) = -\alpha^2(n-1) \tag{15}$$

$$(\nabla_X \eta)(Y) = -\alpha g(Y, \varphi^2 X), \tag{16}$$

for any vector fields X, Y and $\alpha \in \mathbb{R}$. Kenmotsu manifold have been studied by Jun *et al.*, 2006 and he obtained the above results for $\alpha = 1$.

An α -cosymplectic manifold M^n is said to Einstein if its Ricci tensor S is of the form

$$S(X,Y) = \lambda \, g(X,Y) \tag{17}$$

where λ is constant.

3. Semi-Generalized Recurrent α -cosymplectic manifolds

Theorem 3.1.In a semi-generalized Ricci-recurrent α -cosymplectic manifold the 1-form A and B are related as

$$\alpha^2(n-1)A(X) - nB(X) = 0.$$

Proof: A Riemannian manifold (M^n,g) is semi-generalized Ricci-recurrent manifold (Kumar *et al.*, 2010) if

$$(\nabla_X S)(Y, Z) = A(X) S(Y, Z) + n B(X) g(Y, Z).$$
 (18)

Taking $Z = \xi$ in (18), we have

$$(\nabla_X S)(Y,\xi) = A(X)S(Y,\xi) + n B(X)g(Y,\xi). \tag{19}$$

The left hand side of (19), clearly can be written in the form

$$(\nabla_X S)(Y, \xi) = XS(Y, \xi) - S(\nabla_X Y, \xi) - S(Y, \nabla_X \xi),$$

in view of equation (7) and (10) above gives

$$\alpha^3 (n-1)g(Y, \varphi^2 X) + \alpha S(Y, \varphi^2 X).$$

While the right hand side of (19) equals

$$A(X)S(Y,\xi) + nB(X)g(Y,\xi) = -(n-1)\alpha^2 A(X)\eta(Y) + nB(X)\eta(Y).$$

Hence

$$\alpha^{3} (n-1)g(Y, \varphi^{2}X) + \alpha S(Y, \varphi^{2}X) = -(n-1)\alpha^{2}A(X)\eta(Y) + n B(X)\eta$$
 (20)

Putting $Y = \xi$ in (20) and then using (4), (5) and (11), we get

$$-\alpha^2(n-1)A(X) + nB(X) = 0. (21)$$

which proves the theorem.

Theorem 3.2. If a semi-generalized Ricci-recurrent α -cosymplectic manifold is an Einstein manifold then 1-forms A and B are related as λ A(Y) + n B(Y).

Proof. For an Einstein manifold, we have $S(Y, Z) = \lambda g(Y, Z)$ and $(\nabla_U S) = 0$, where λ is constant.

Hence from (18), we have

$$[\lambda A(X) + nB(X)]g(Y,Z)] + [\lambda A(Y) + nB(Y)]g(Z,X)]$$
$$+[\lambda A(Z) + nB(Z)]g(X,Y) = 0.(22)$$

Replacing Z by ξ in (22) and using (2), (4) and (5), we have

$$\lambda \eta(P) + n \, \eta(Q) = 0. \tag{23}$$

Using (4) in the above equation, it follows that

$$\lambda A(Y) + n B(Y). \tag{24}$$

4. Semi-Generalized φ -Recurrent α -cosymplectic manifolds

Definition4.1.A α -cosymplectic manifolds (M^n, g) is called semi-generalized φ -recurrent if its curvature tensor R satisfies the condition

$$\varphi^2((\nabla_W R(X,Y)Z) = A(W)R(X,Y)Z + B(W)g(Y,Z)X,\tag{25}$$

where A and B are two 1-forms, B is non-zero and these are defined by

$$A(W)=g(W,P)$$
 and $B(W)=g(W,Q), (W,P),$ (26)

and P and Q are vector fields associated with 1-forms A and B respectively.

Theorem 4.1. A semi-generalized φ -recurrent α -cosymplectic manifold (M^n, g) is an Einstein manifold.

Proof. Let us consider a semi –generalized φ -recurrent α -cosymplectic manifold. Then by virtue of (3) and (25) we have

$$-(\nabla_{W}R)(X, Y)Z + \eta((\nabla_{W}R)(X, Y)Z)\xi = A(W)R(X, Y)Z + B(W)g(Y, Z)X,$$
 (27)

from which it follows that

$$-g((\nabla_W R)(X, Y) Z, U) + \eta((\nabla_W R)(X, Y) Z)(U)$$

$$= A(W) g(R(X, Y)Z, U) + B(W) g(Y, Z) g(X, U).$$
(28)

Let $\{e_i\}$, i=1, 2, 3.....n be an orthonormal basis of the Tangent space at any point of the manifold. Then putting $X = U = e_i$ in (28) and taking summation over i, $1 \le i \le n$, we get

$$(\nabla_{W}S)(Y,Z) + \sum_{i=1}^{n} \eta((\nabla_{W}R)(e_{i},Y,Z)\eta(e_{i})$$

$$= A(W)S(Y,Z) + n B(W)g(Y,Z).$$
(29)

The second term of left hand side of (27) by putting $Z = \xi$ takes the form $g((\nabla_W R) (e_i, Y) \xi, \xi)$, which is zero in this case. So, by replacing Z by ξ in (27) and using (10) we get

$$(\nabla_{W}S)(Y,\xi) = -\alpha^{2}(n-1) A (W) \eta(Y) - n B (W) \eta(Y).$$
(30)

Now, we have

$$(\nabla_W \mathbf{S})(\mathbf{Y},\,\xi) = \nabla_W \mathbf{S}(\mathbf{Y},\,\xi) - \mathbf{S}(\nabla_W \mathbf{Y},\,\xi) - \mathbf{S}(\mathbf{Y},\,\nabla_W \xi).$$

Using (7) and (10) in the above relation, it follows

$$(\nabla_{WS}(Y,\xi) = (n-1)\alpha^3 g(\varphi^2 W,Y) + \alpha S(Y,\varphi^2 W), \tag{31}$$

From (30) and (31) we obtain

$$(n-1)\alpha^3 g(\varphi^2 W, Y) + \alpha S(Y, \varphi^2 W) = -\alpha^2 (n-1)A(W)\eta(Y) - n B(W)\eta(Y)$$
(32)

Replacing $Y = \xi$ in (32) then using (3) we get

$$-\alpha^{2}(n-1)A(W) = n B(W). \tag{33}$$

Using (33) in (32), we obtain

$$S(Y, \varphi^2 W) = -(n-1)\alpha^2 g(Y, \varphi^2 W).$$
 (34)

In consequence of the equations (3) and (7) the above equation reduces to

$$S(Y,W) = -(n-1)\alpha^2 g(Y,W),$$

which shows that the manifold is Einstein manifold.

Theorem 4.2. In a semi-generalized φ -recurrent α -cosymplectic manifold the characteristic vector field (P+Q) associated to the 1-form A + B are given by

A (W) =
$$\left[\frac{2}{(n-2)\alpha^2}\eta(Q) - \frac{1}{(n-2)}\eta(P)\right]\eta(W)$$
.

Proof.From the relation (25), we have

$$(\nabla_{W}R)(X,Y)Z = \eta((\nabla_{W}R)(X,Y)Z)\xi - A(W)R(X,Y)Z - B(W)g(Y,Z)X.$$
(35)

Then by use of second Bianchi's identity and (35), we get

$$A(W) \eta(R(X, Y) Z) + A(X) \eta(R(Y, W) Z) + A(Y) \eta(R(W, X) Z)$$

+B (W)
$$g(Y, Z) \eta(X)$$
 +B(X) $g(W, Z) \eta(Y)$ +B(Y) $g(X, Z) \eta(W)$ =0. (36)

By virtue of (13) we obtain from (36)

$$[-\alpha^2 \text{ A (W)} + \text{B (W)}] g(Y, Z) \eta(X) + [-\alpha^2 \text{ A (X)} + \text{B (X)}] g(W, Z) \eta(Y)$$

$$+ [-\alpha^2 A (Y) + B (Y)] g(X, Z) \eta(W) + \alpha^2 A (W) g(X, Z) \eta(Y)$$

$$+\alpha^2 A(X) g(Y, Z) \eta(W) + \alpha^2 A(Y) g(W, Z) \eta(X) = 0.$$
 (37)

Putting Y = Z= e_i in (37), using (33) and taking summation over i, $1 \le i \le n$, we get

$$(n-2)\alpha^2 A(W)\eta(X) = [2B(X) - \alpha^2 A(X)]\eta(W), \tag{38}$$

for all vector fields X, W. Replacing X by ξ in (38) it follows that

$$A(W) = \left[\frac{2}{(n-2)\alpha^2}\eta(Q) - \frac{1}{(n-2)}\eta(P)\right]\eta(W)$$
 (39)

for any vector field W, where A $(\xi) = g(\xi, P) = \eta(P)$ and B $(\xi) = g(\xi, Q) = \eta(Q)$.

This completes the proof.

5. Semi-Generalized φ-Recurrent M-Projective α-cosymplectic manifolds

Definition 5.1. A α - cosymplectic manifold (M^n, g) is called semi-generalized M-Projective φ -recurrent if it's M-Projective curvature tensor (Pokhariyal and Mishra, 1971) given by

$$W^*(X,Y)Z = R(X,Y)Z - \frac{1}{2(n-1)}[S(Y,Z)X - S(X,Z)Y + g(Y,Z)QX - g(X,Z)QY], \quad (40)$$

satisfies the condition

$$\varphi^{2}((\nabla_{V}W^{*})(X, Y)Z) = A(V)W^{*}(X, Y)Z + B(V)g(Y, Z)X(41)$$

where A and B are defined as (26).

Theorem 5.1. Let (M^n,g) be a semi-generalized M-projective φ - recurrent α -cosymplectic manifold then

$$\left[\frac{-n(n-1)\alpha^2-r}{2(n-1)}\right] A(V) + n B(V) = 0.$$

Proof: Let us consider a semi-generalized φ -recurrent α -cosymplectic manifold. Then by virtue of (3) and (41) we have

$$-(\nabla_{V}W^{*})(X, Y) Z + \eta ((\nabla_{V}W^{*})(X, Y) Z) \xi = A(V) W^{*}(X, Y) Z + B(V) g(Y, Z) X.$$
 (42)

From which it follows that

$$-g((\nabla_V W^*)(X, Y) Z, U) + \eta((\nabla_V W^*)(X, Y) Z) \eta (U)$$

$$= A(V)g(W^*(X, Y) Z, U) + B(V) g(Y, Z) g(X, U). \tag{43}$$

Let $\{e_i\}$, i=1, 2, 3.....n be an orthonormal basis of the Tangent space at any point of the manifold. Now putting $X = U = e_i$ in (43) and taking summation over i, $1 \le i \le n$, we get

$$-\frac{n}{2(n-1)} (\nabla_{V} S)(X, U) + \frac{1}{2(n-1)} V(r) g(X, U)$$

$$+ \frac{n}{2(n-1)} (\nabla_{V} S) (X, \xi) \eta (U) - \frac{1}{2(n-1)} V(r) \eta(X) \eta(U)$$

$$= A (V) \left[\frac{n}{2(n-1)} S(X, U) - \frac{r}{2(n-1)} g(X, U) \right] + n B (V) g(X, U).$$
(44)

Replacing U by ξ in (44) and using (3) and (10) we get

$$\left[\frac{-n(n-1)\alpha^{2}-r}{2(n-1)}\right] A (V) \eta(X) + n B (V) \eta(X) = 0.$$
 (45)

Putting $X = \xi$ in (45), we obtain

$$\left[\frac{-n(n-1)\alpha^{2}-r}{2(n-1)}\right] A (V) + n B (V) = 0.$$
 (46)

This proves the theorem.

Theorem5.2. A semi-generalized M-Projective φ -recurrent α -cosymplectic manifold is an Einstein manifold.

Proof. Putting $X = U = e_i$ in (28) and taking summation over i, $1 \le i \le n$, we get

$$\begin{split} -\frac{n}{2(n-1)} (\nabla_V S) \ (Y,Z) &= - \ \frac{1}{2(n-1)} \ V(r) \ g(Y,Z) - g((\nabla_V R) \ (e_i, \, Y) \ Z, \, \xi) \ g(e_i, \, \xi) \\ &+ \frac{1}{2(n-1)} \left[(\nabla_V S) \ (Y,Z) \ g(\xi,\xi) \ - (\nabla_V S) \ (\xi,Z) \ g(Y,\xi) \right] \end{split}$$

$$-(\nabla_{V}S)(\xi,\xi)g(Z,\xi)] + \left[\frac{n}{2(n-1)}S(Y,Z) - \frac{r}{2(n-1)}g(Y,Z)\right]A(V) + nB(V)g(Y,Z). \tag{47}$$

Replacing Z by ξ in (47) and using (3) and (10) we get

$$(\nabla_V S(Y, \xi) = \frac{1}{n} V(r) \eta(Y). \tag{48}$$

Now, we have

$$(\nabla_V \mathbf{S})(\mathbf{Y},\,\xi) = \nabla_V \mathbf{S}(\mathbf{Y},\,\xi) - \mathbf{S}(\nabla_V \mathbf{Y},\,\xi) - \mathbf{S}(\mathbf{Y},\,\nabla_V \xi).$$

Using (7) and (10) in above relation, it follows that

$$(\nabla_V S)(Y, \xi) = \alpha^3 (n-1) g(Y, \varphi^2 V) + \alpha S(Y, \varphi^2 V).$$
 (49)

In view of (48) and (49) we have

$$\frac{1}{n}V(r)\eta(Y) = \alpha^{3}(n-1)g(Y,\varphi^{2}V) + \alpha S(Y,\varphi^{2}V).$$
 (50)

Replacing Y by φ Y in (50) then using (5), (9) and (11), we obtain

$$S(\varphi Y, V) = \alpha^2 (n-1) g(\varphi Y, V). \tag{51}$$

Again, Replacing V by φ V in (51), we obtain

$$S(Y, V) = \alpha^2 (n-1) g(Y, V).$$
 (52)

This prove the theorem

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